

MOTION DYNAMICS OF UTOPUS PUSH-PULL VEHICLE WITH NARROW TINES FOR TRACTION

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UTOPUS is a new locomotion system based on crampons which are periodically inserted into the soil. Here we investigate the energy profile of the resulting motion cycle.

Introduction: traction by crampon



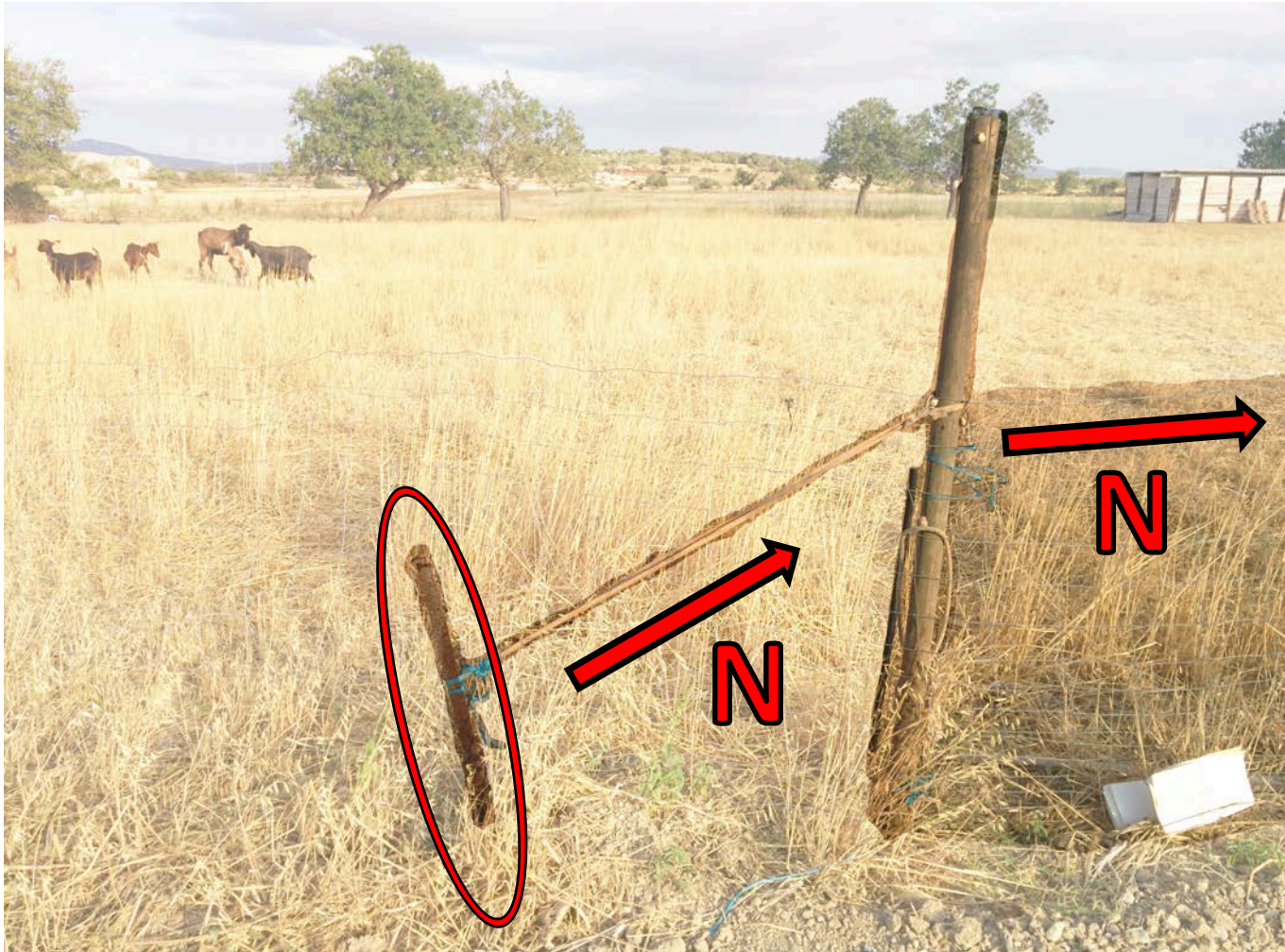
Introduction: traction by crampon

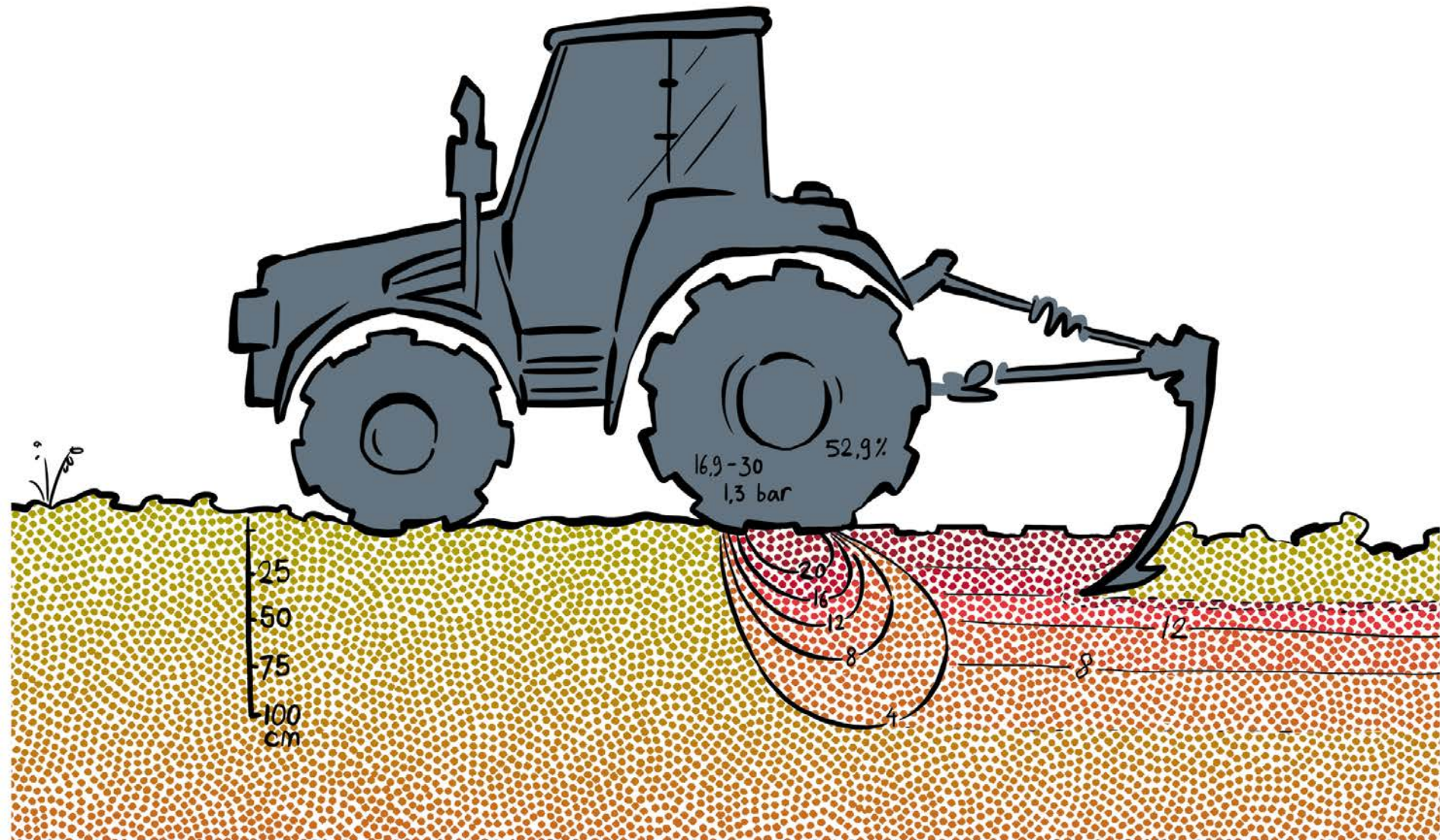
Inspiration:
Pole or peg
which holds
fence



Introduction: traction by crampon

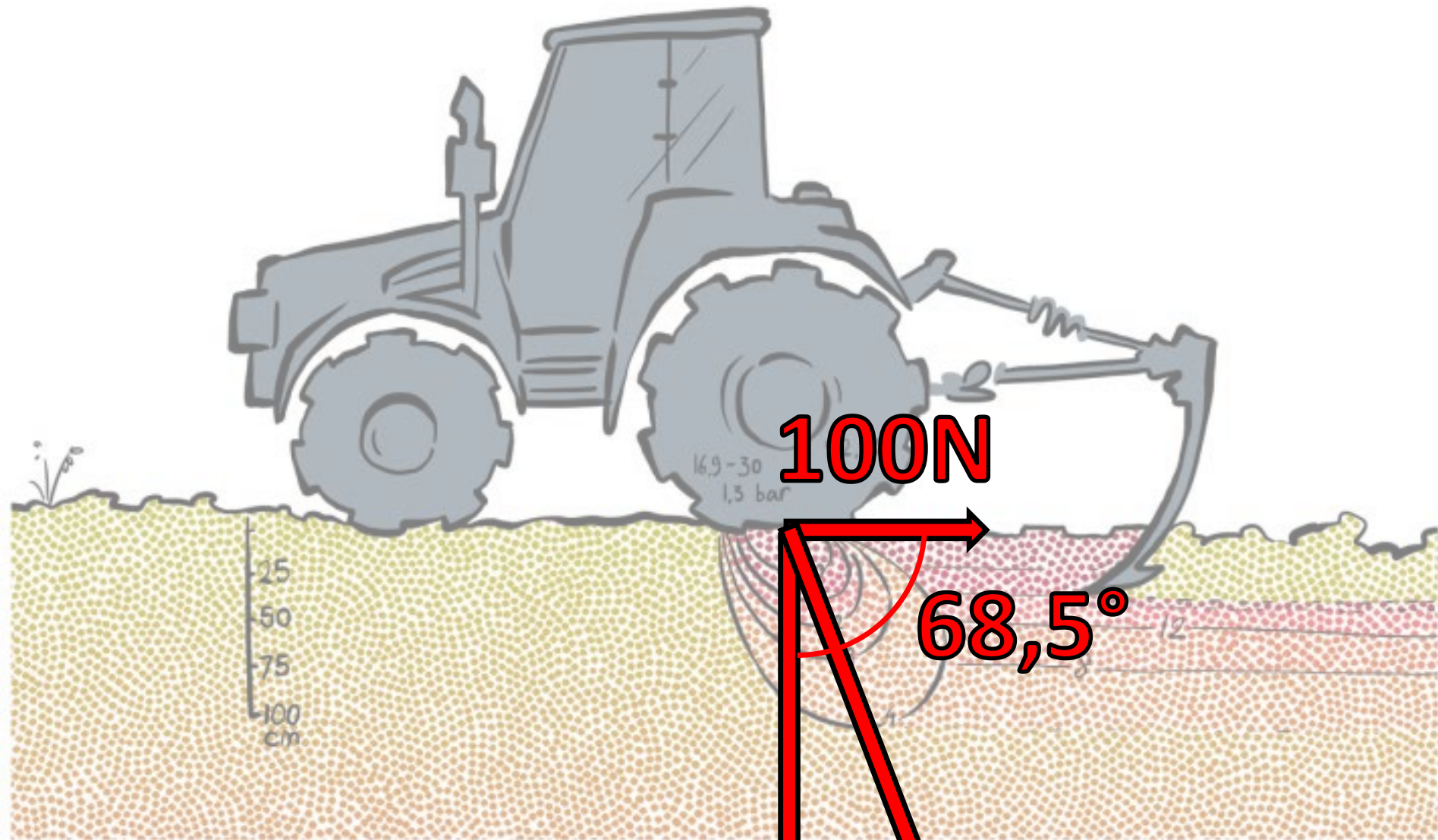
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Pole or peg
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ANIMOSHE

Traction by wheel is based on ballast.

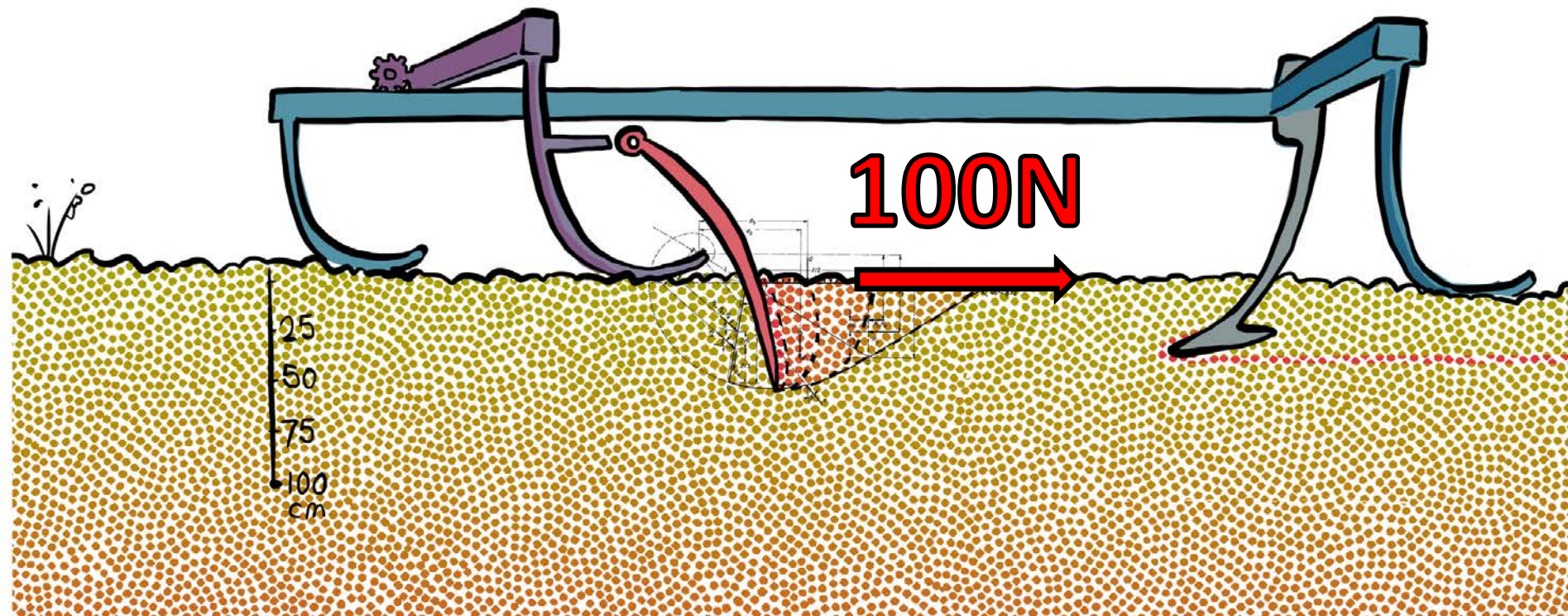


Traction by wheel is based on ballast.

250N

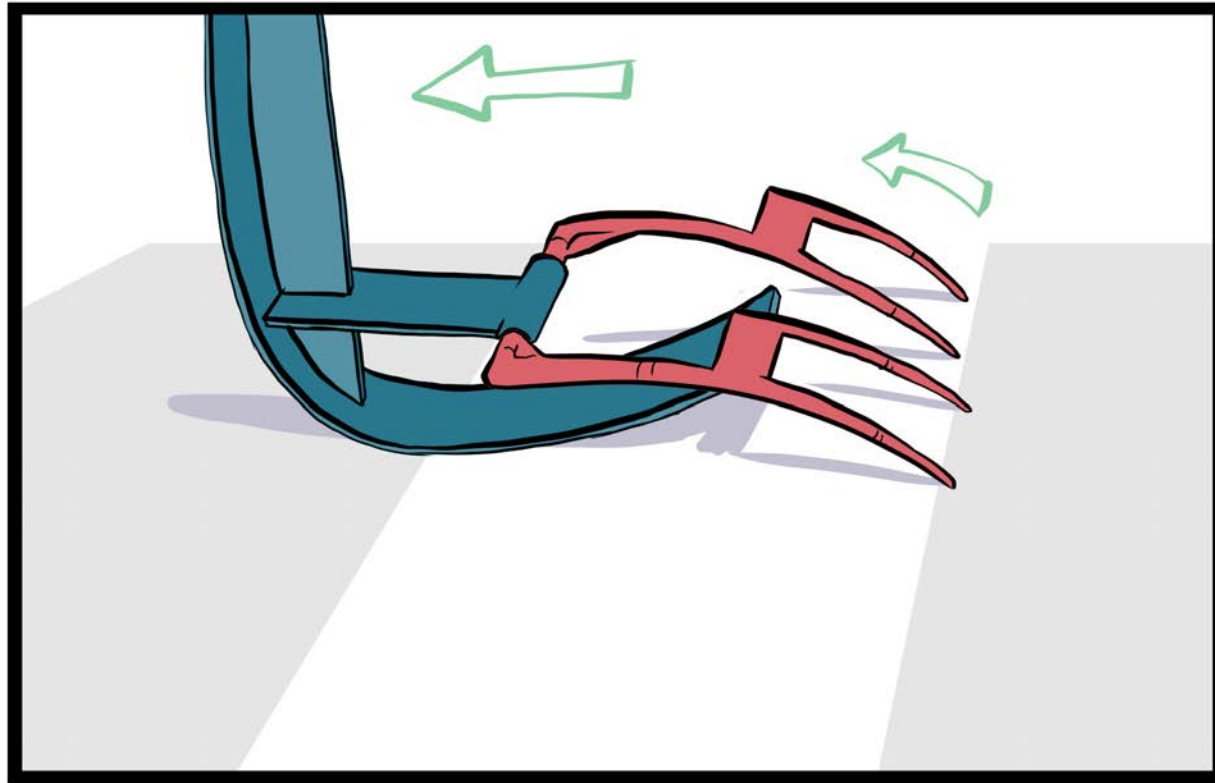
269N

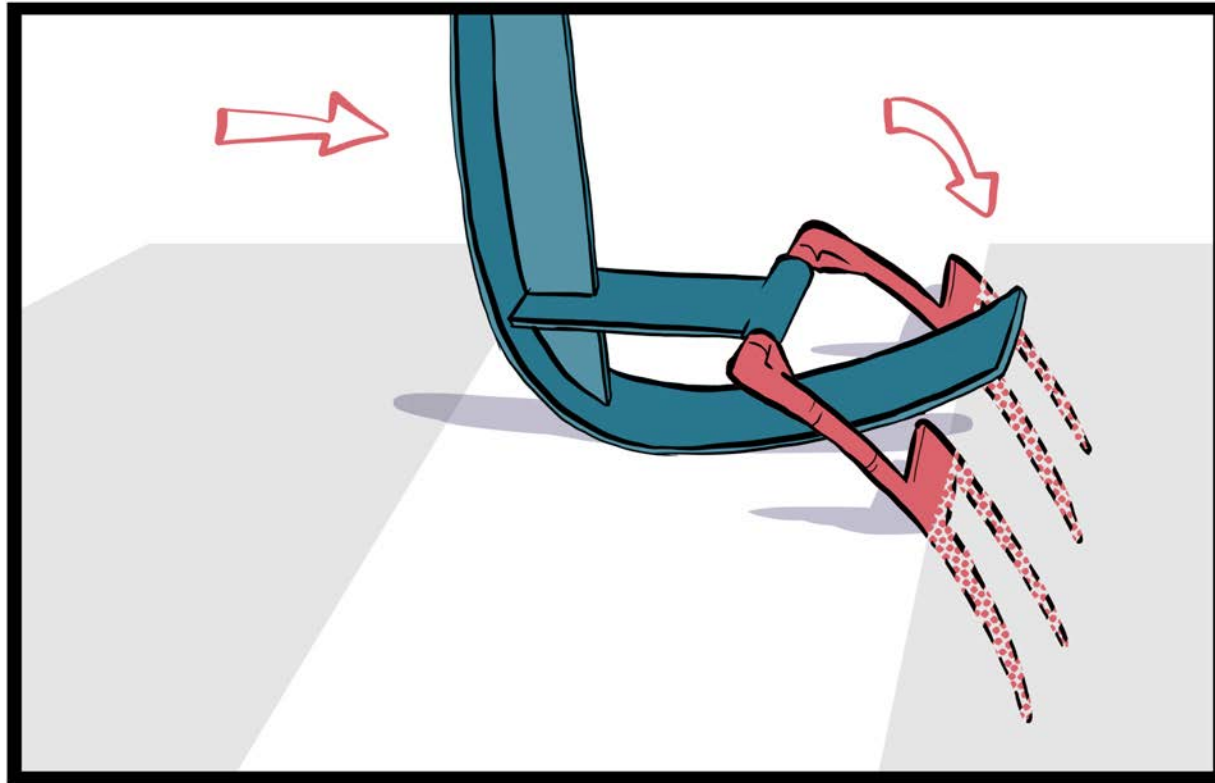
ANIMOSHE



Traction by
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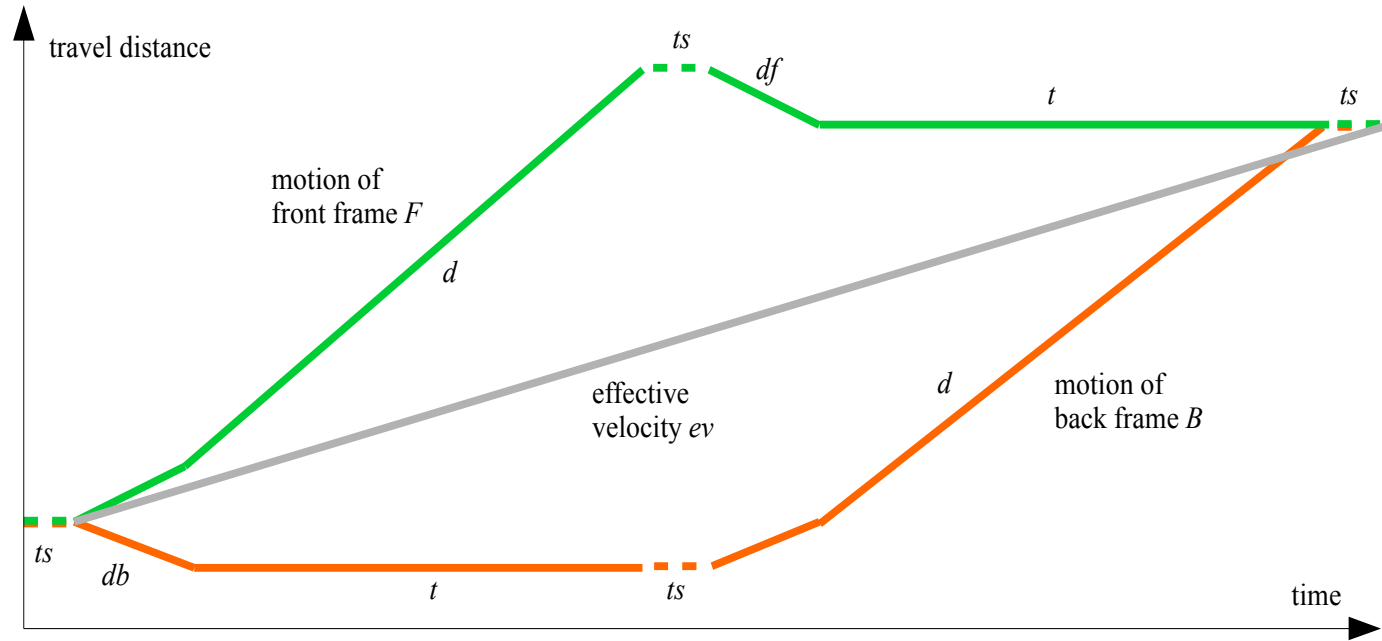
while crampons
press only sideways.





UTOPUS in motion

1. Full contraction



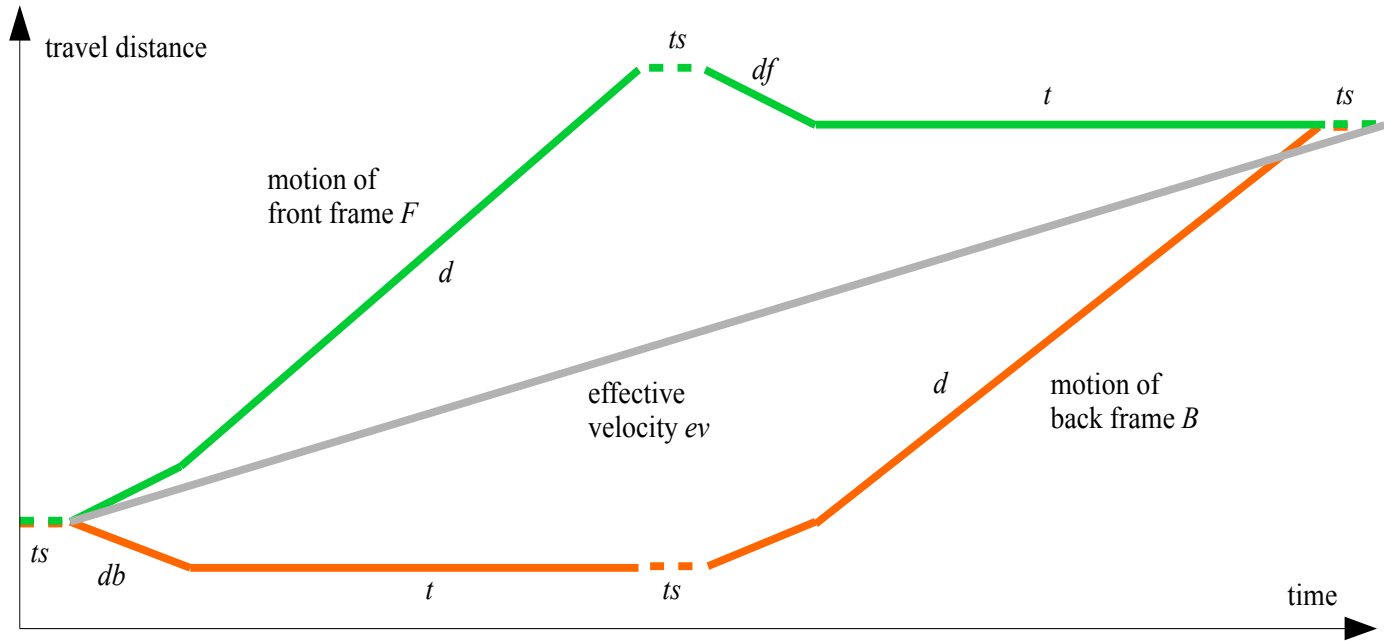
Crampon of rearward moving frame OUT OF soil

Crampon of fixed front frame INSIDE soil

UTOPUS in motion

2. Starting expansion

Note how this frame moved ~ 5 cm BACKWARDS to anchor

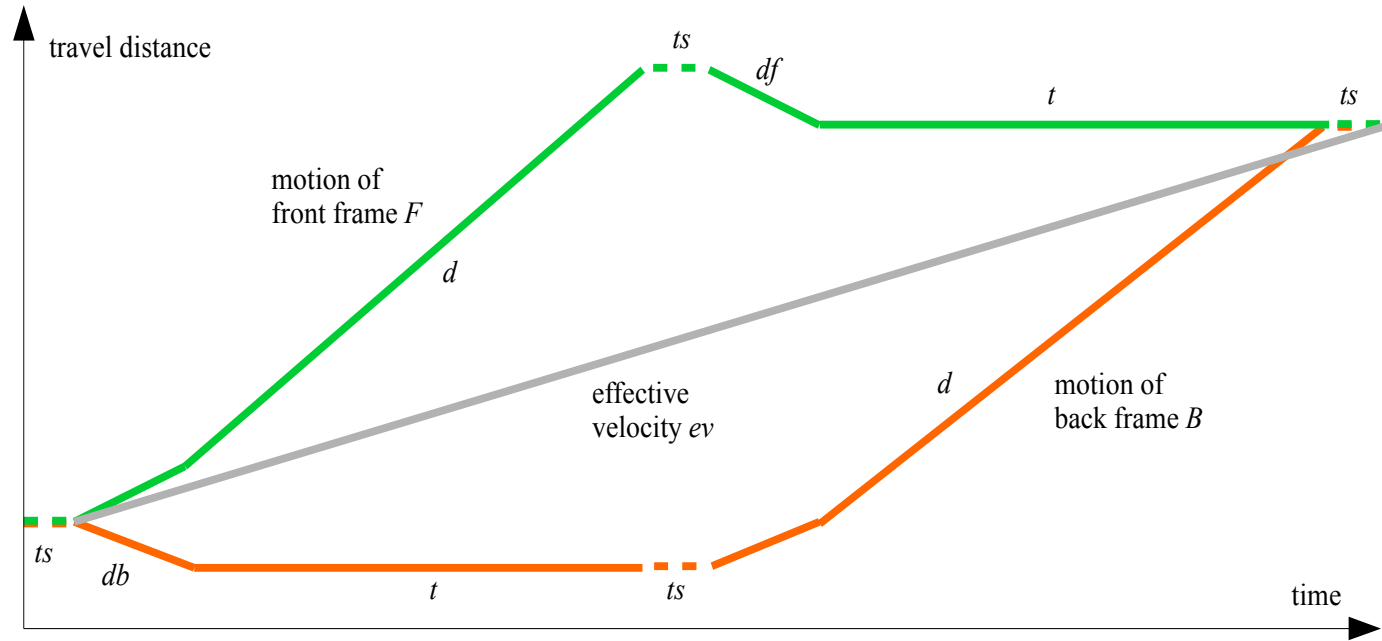


Crampon of rearward moving frame INSIDE soil

Crampon of fixed front frame OUT OF soil

UTOPUS in motion

3. Full expansion

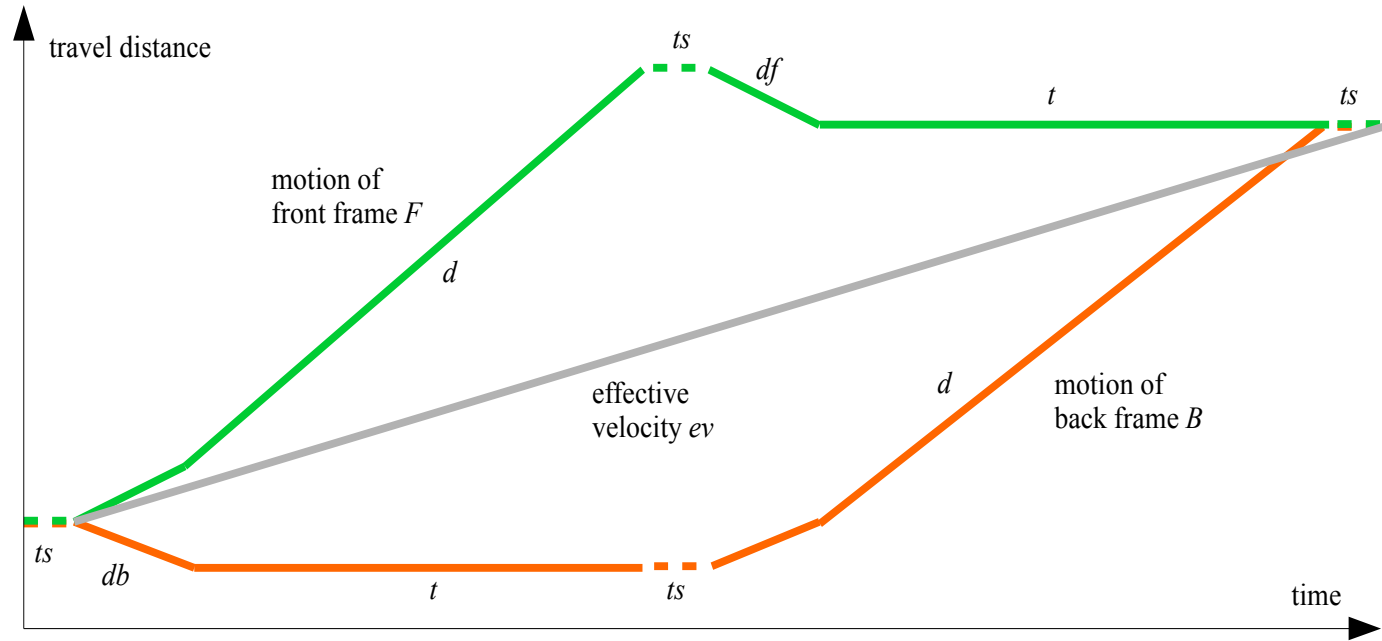


Crampon of rearward moving frame INSIDE soil

Crampon of fixed front frame OUT OF soil

UTOPUS in motion

4. Starting contraction



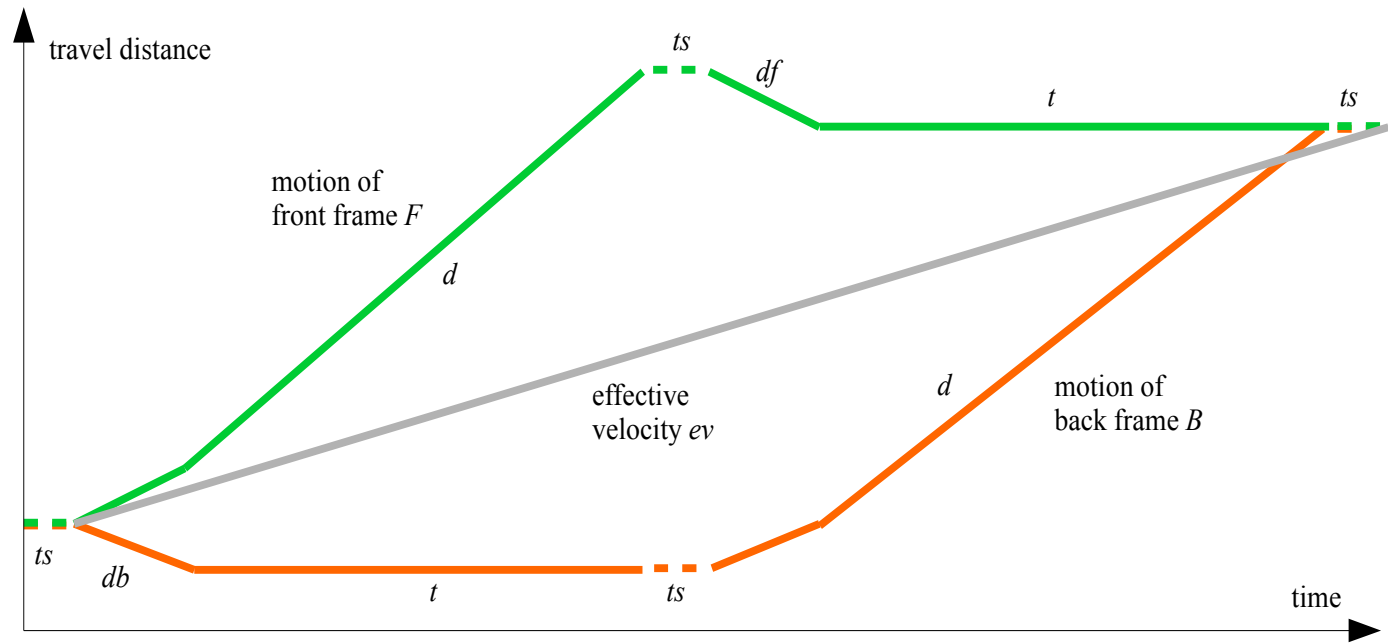
Crampon of rearward moving frame OUTSIDE soil

Crampon of fixed front frame INSIDE soil

Note how frame moved ~ 20 cm BACKWARDS to anchor

UTOPUS in motion

5. Contracting

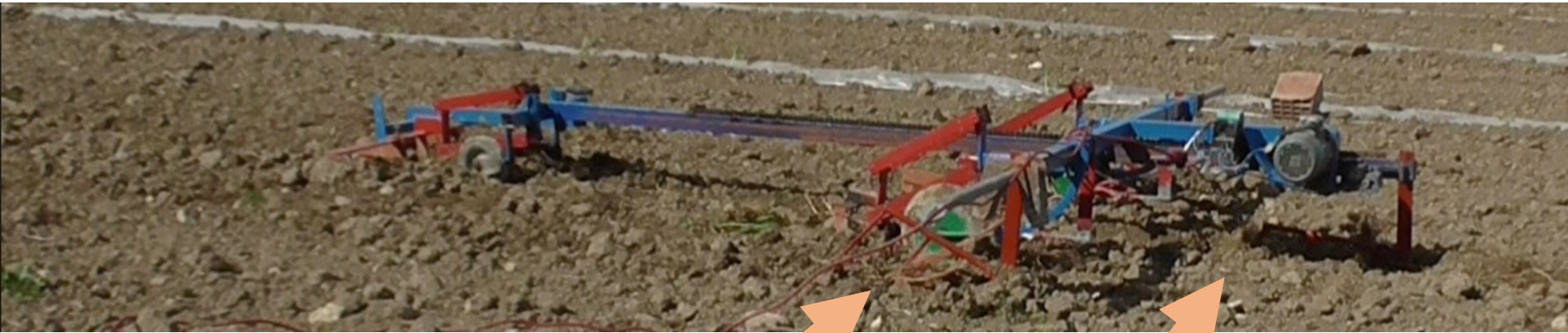
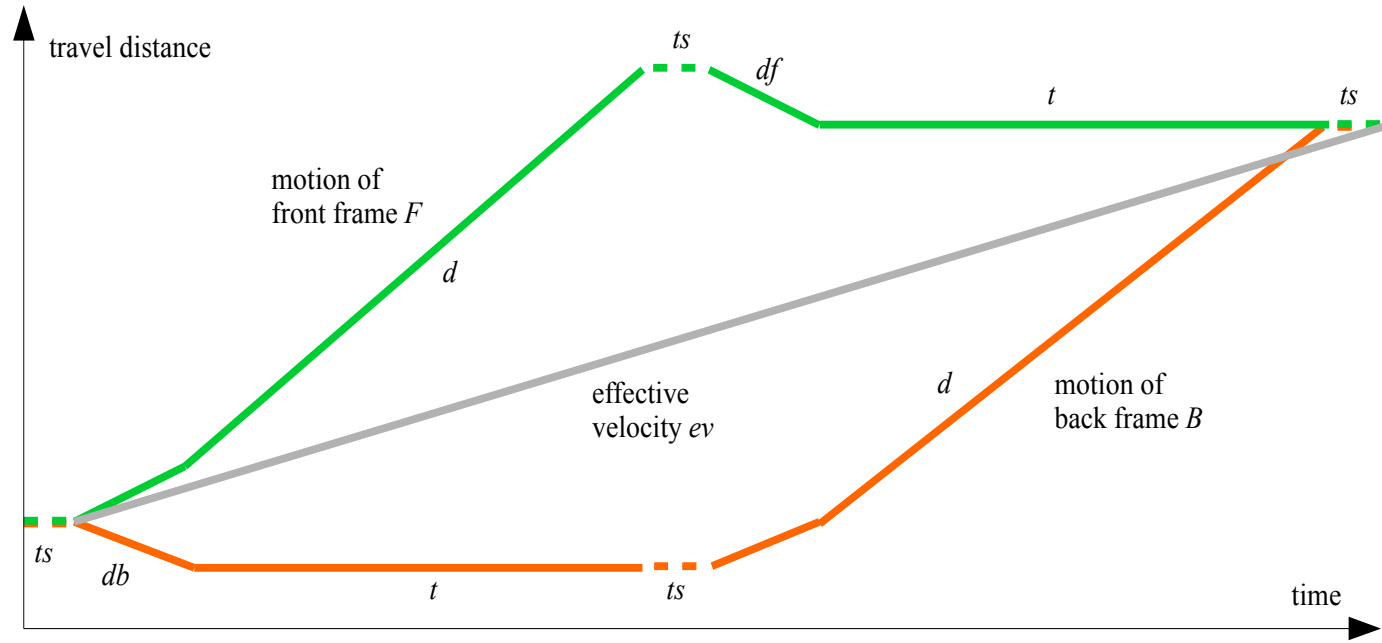


Crampon of rearward moving frame OUTSIDE soil

Crampon of fixed front frame INSIDE soil

UTOPUS in motion

6. Full contraction



Crampon of rearward moving frame OUTSIDE soil

Crampon of fixed front frame INSIDE soil

Experiment: energy profile of a push-pull motion cycle

Several experiments on agricultural land in Vilafranca de Bonany, Mallorca, Spain.

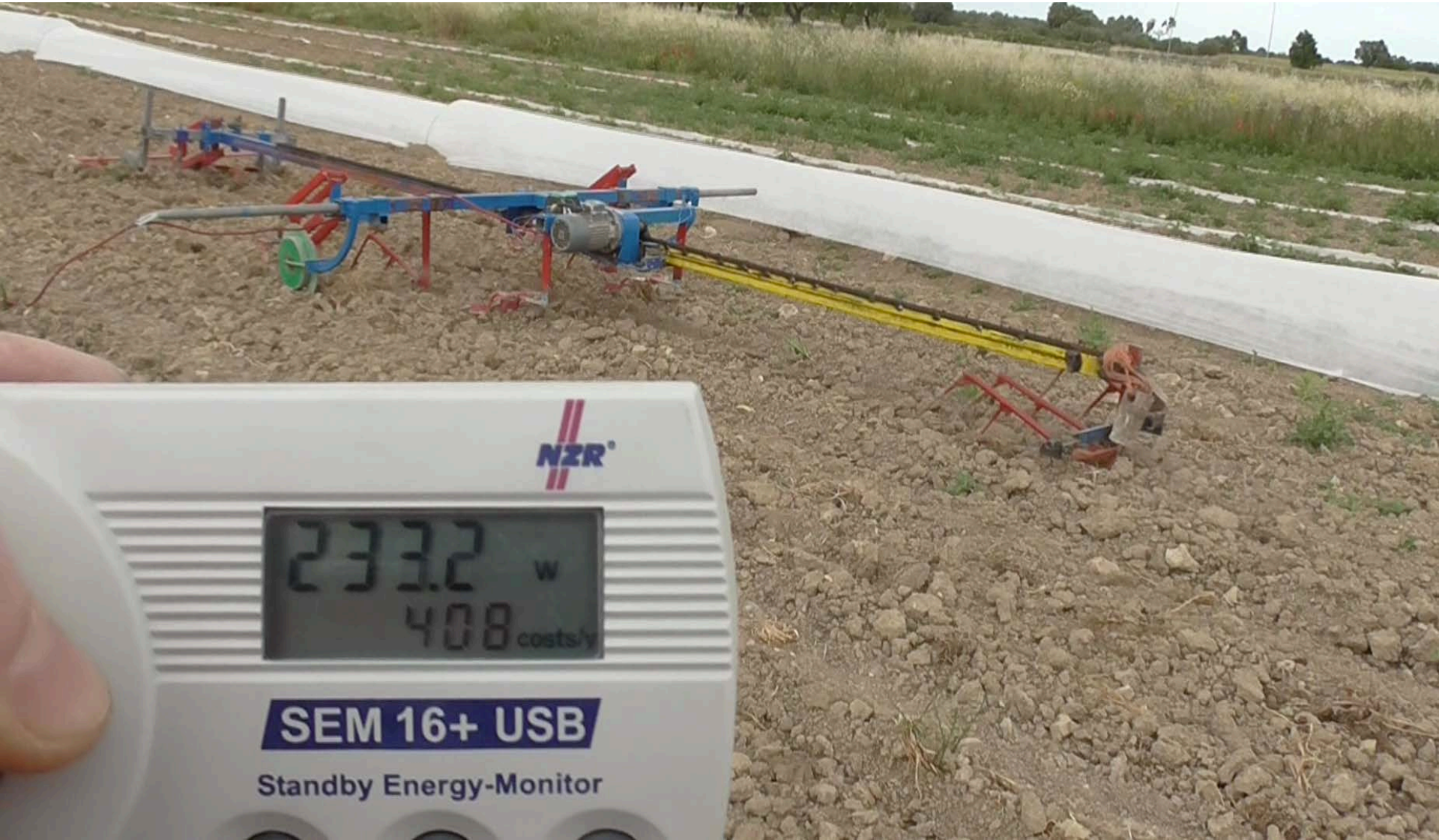
Electrical machine.

Accurate Watt meter with 0.83 s resolution.

Plow depth is 3–5 cm.

Length of central axis is 4.025 m
(vehicle length: 5m).

Experiment: energy profile of a push-pull motion cycle



Experiment: energy profile of a push-pull motion cycle

The drive train consists of an asynchronous electric motor, cogwheel, chain, and variable frequency drive.



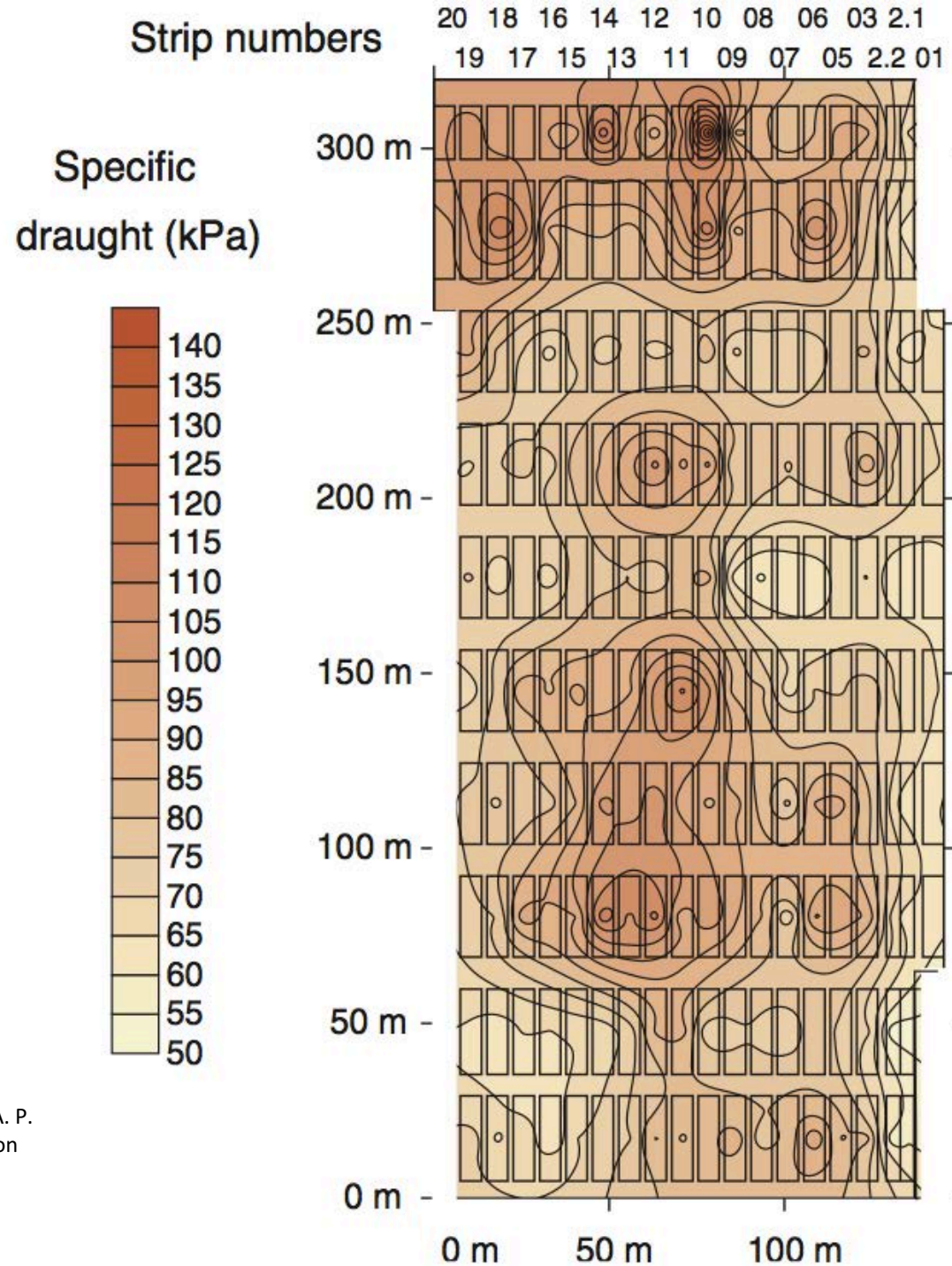
The tillage tools tools are optimized for low speed:

Local designs from horse drawn implements.



Soil resistance is very heterogeneous.

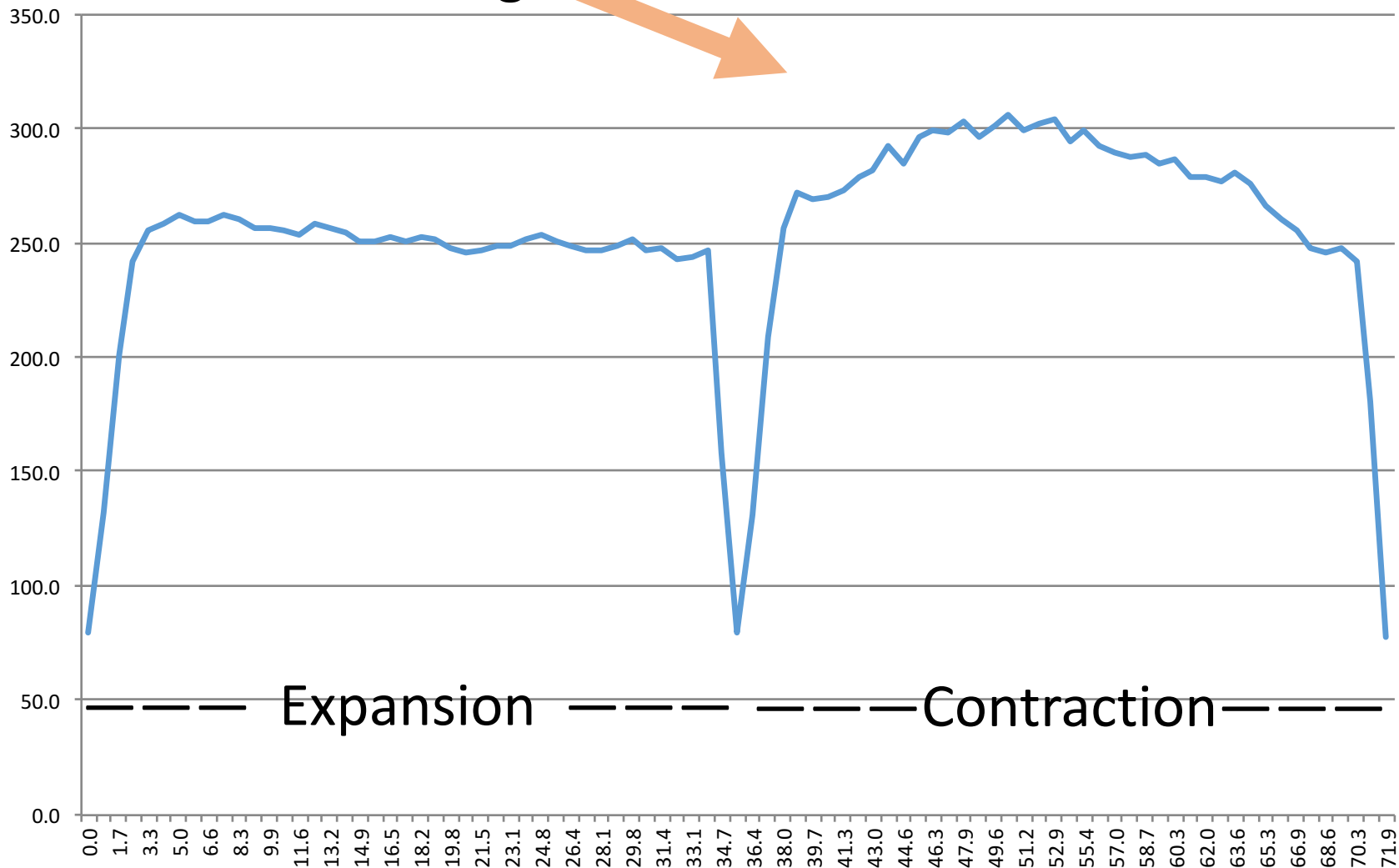
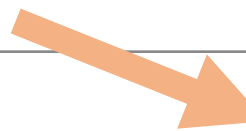
Draft varies
+/- 50%
within 10m.



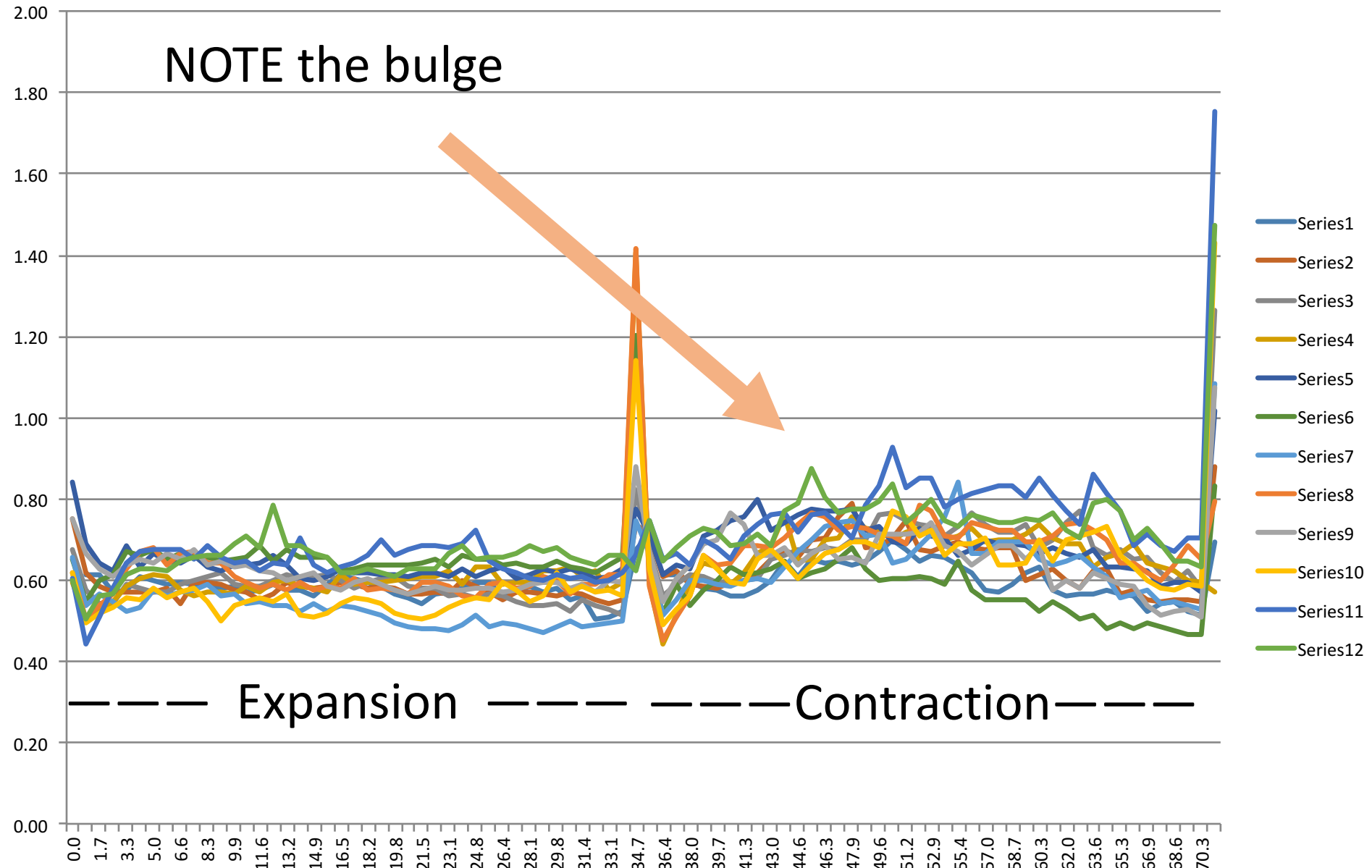
Watts, C. W., Clark, L. J., Poulton, P. R., Powlson, D. S., & Whitmore, A. P. (2006). The role of clay, organic carbon and long-term management on mouldboard plough draught measured on the Broadbalk wheat experiment at Rothamsted. *Soil Use Manag.*, 22(4), 334–341. <http://doi.org/10.1111/j.1475-2743.2006.00054.x>

Electricity consumption over 12 motion cycles AVERAGED

NOTE the bulge

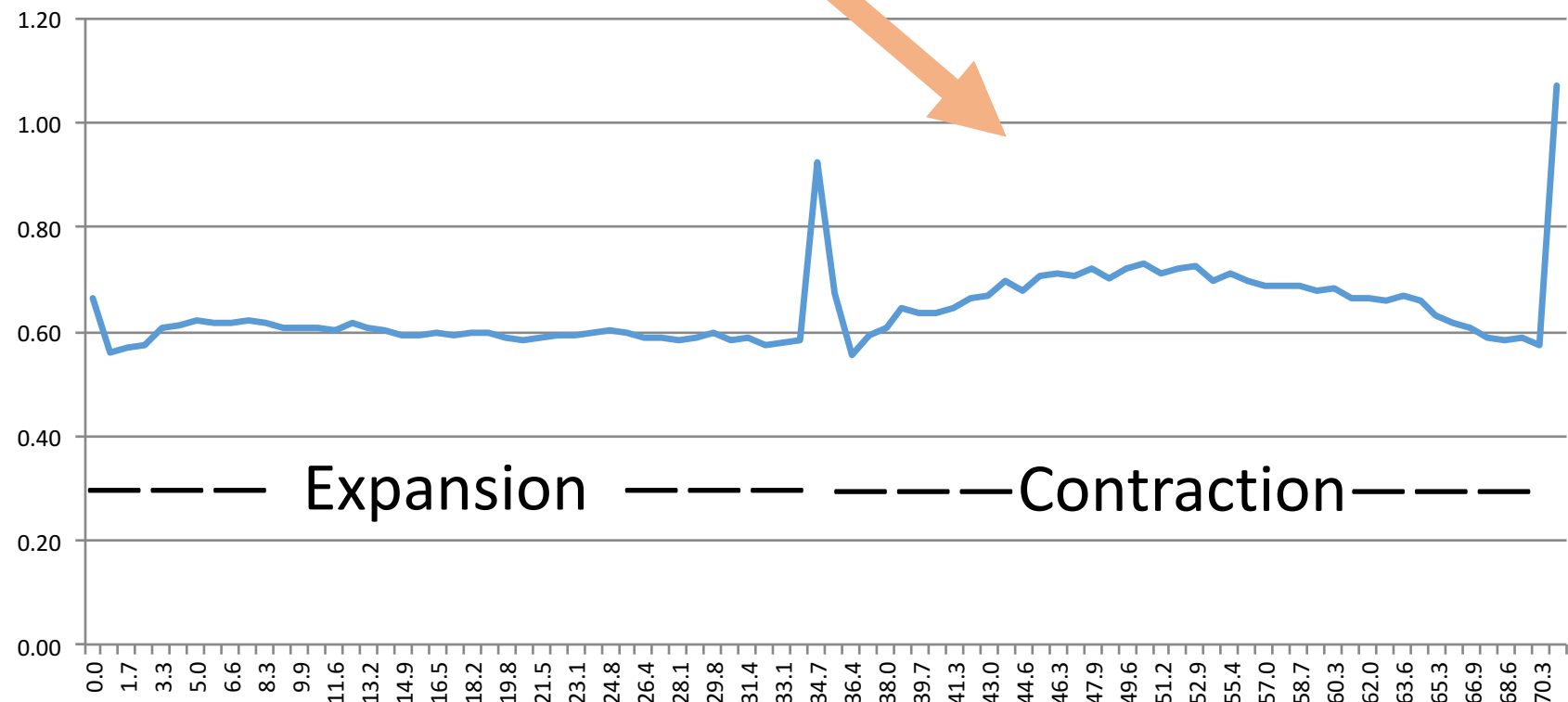
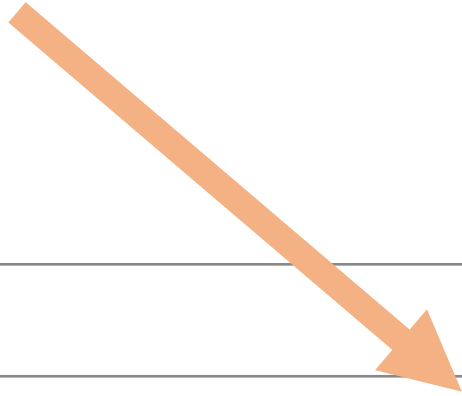


Drawbar pull for 12 motion cycles



Drawbar pull for 12 motion cycles, AVERAGED

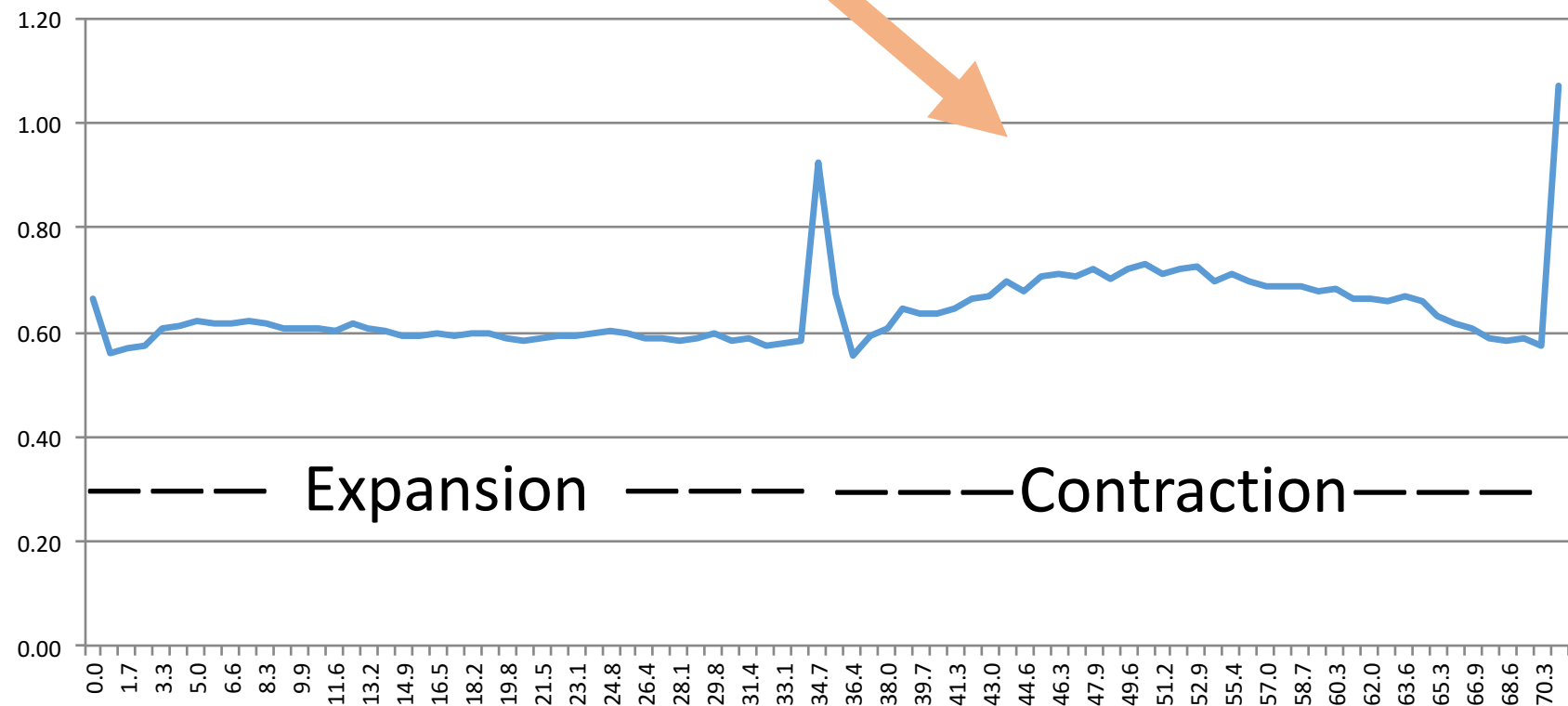
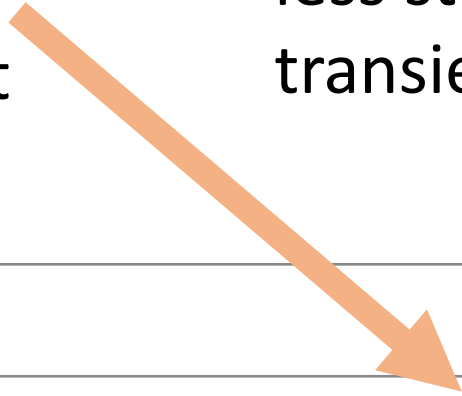
NOTE the bulge.



Drawbar pull for 12 motion cycles, AVERAGED

Possible explanations include change in depth of the front plow.

In any case: PUSH-PULL means less steady state and more transient phenomena.



After 12 cycles:

The cogwheel has travelled 48.3 m.

The plow has travelled 45.2 m.

On average 13 cm are lost to anchor the crampons.

Travel reduction: 6.4%

To calculate tractive efficiency, we need a good estimate of drawbar pull but drawbar pull does not reach a steady state during contraction.

Each expansion and each contraction lasts 35 seconds.

Based on seconds 25–35, tractive efficiency is 90%.

Based on seconds 15–35, tractive efficiency is 93%.

Based on seconds 5–35, tractive efficiency is 94%.

Tractors have tractive efficiency of <80% (often 70%).

Conclusion for crampon based traction:

Tractive efficiency depends on vehicle length.

A tractive efficiency of 90%–94% can be achieved with a vehicle length of 5 m.

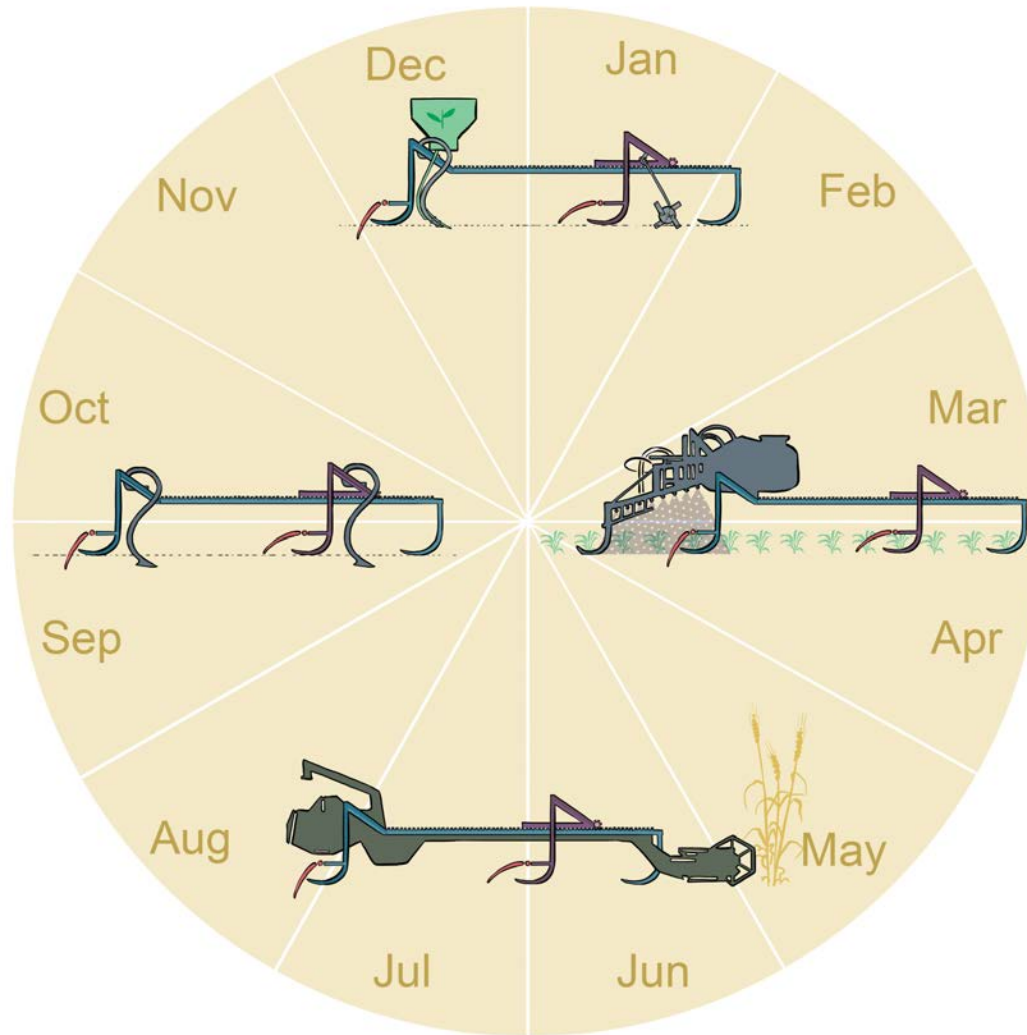
PUSH-PULL means less steady state and more transient phenomena.

The concepts of inserting crampons into the soil and then pushing or pulling from them cannot be treated as separate phases of the motion cycle.

The way the tines settle in the soil affects the motion dynamics and energy consumption of the vehicle during the push/pull phase.

This needs to be taken into account for low level motion control, and calls for special mounts for tools like plow shares to optimize interaction with the soil.

Thank you!



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